

# Deep kernel video approximation for unsupervised action segmentation

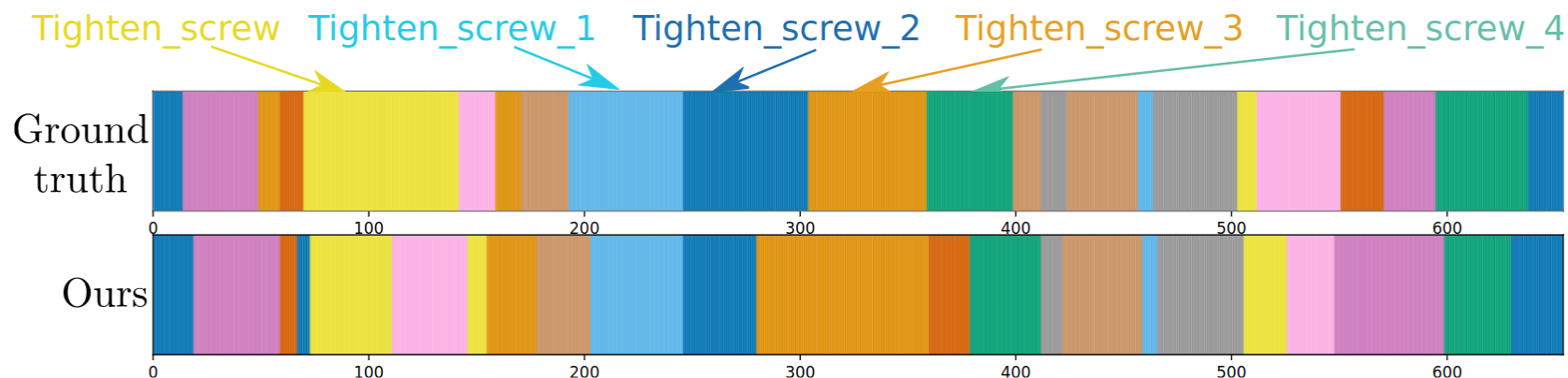


<sup>1</sup>S.L. Pinteá and <sup>2</sup>J. Dijkstra

<sup>1</sup>Tilburg University, Netherlands

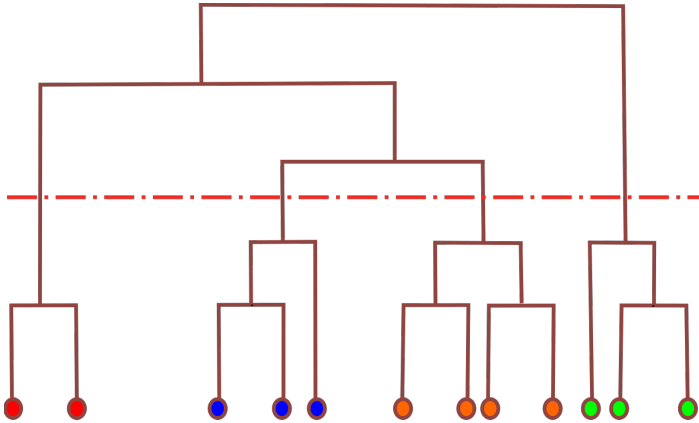
<sup>2</sup>Leiden University Medical Center, Netherlands

# Unsupervised action segmentation



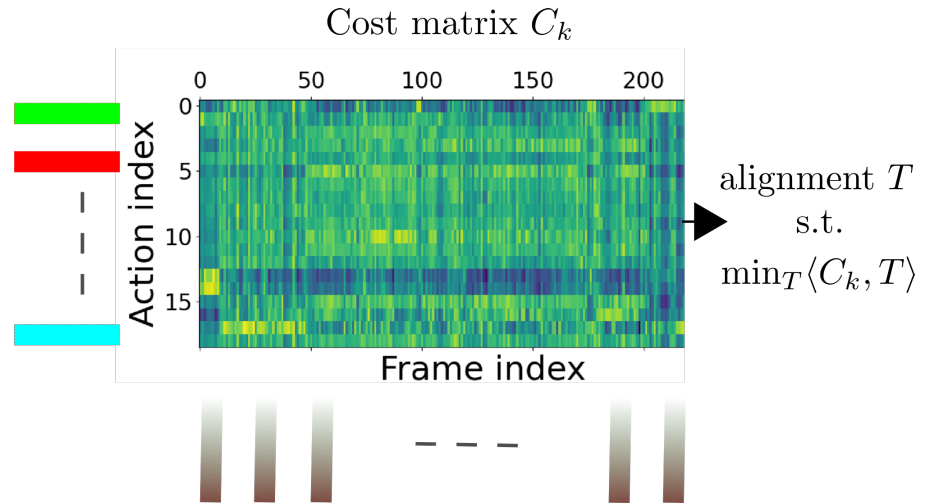
- **Aim:** Detect *unitary* actions in videos
  - How do we define what a *unitary* action is?

# Prior work



- S. Sarfraz, et. al., “*Temporally-weighted hierarchical clustering for unsupervised action segmentation*”, in CVPR, 2021.

- Z. Du, et. al., “*Fast and unsupervised action boundary detection for action segmentation*”, in CVPR, 2022.



- M. Xu and S. Gould, “*Temporally consistent unbalanced optimal transport for unsupervised action segmentation*”, in CVPR, 2024.

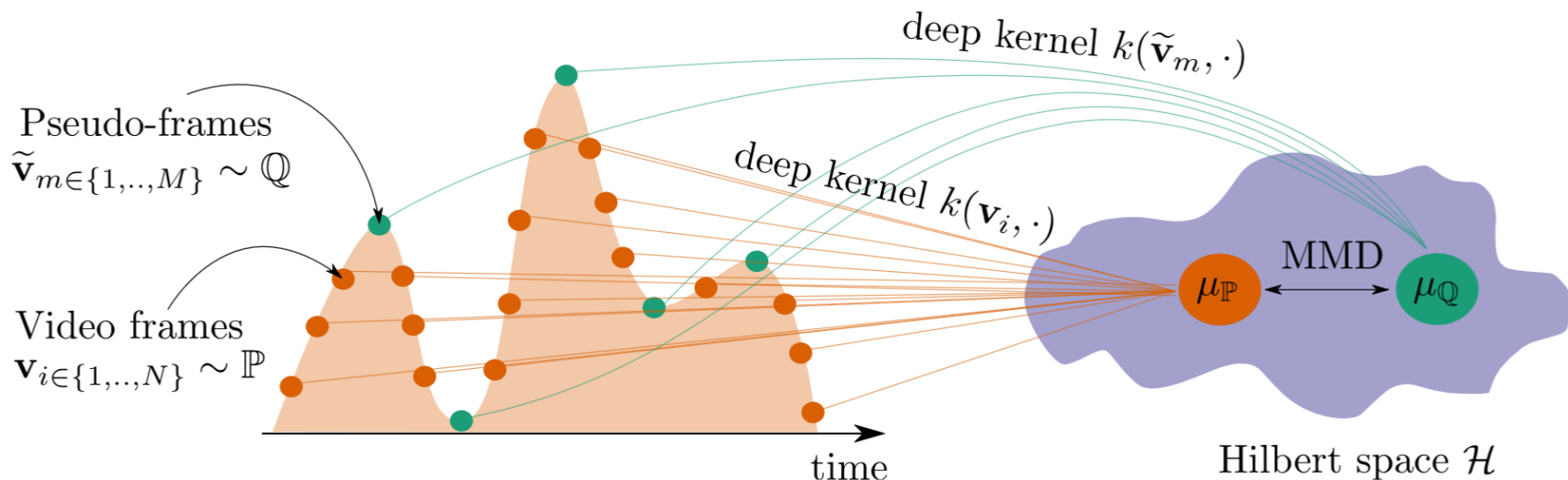
- E. Bueno-Benito and M. Dimiccoli, “*Clot: Closed loop optimal transport for unsupervised action segmentation*”, in ICCV, 2025.

# Learning video approximations

- Single video processed at a time (sensitive data: e.g. hospitals)

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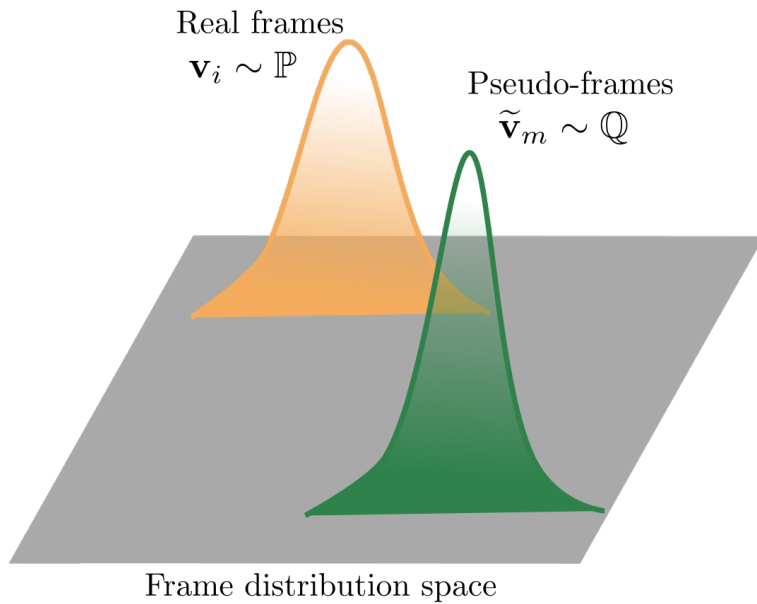
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- Learn pseudo-frames  $\tilde{\mathbf{v}}_m \sim \mathbb{Q}$  such that they approximate "as close as possible" the distribution of real frames  $\mathbf{v}_i \sim \mathbb{P}$

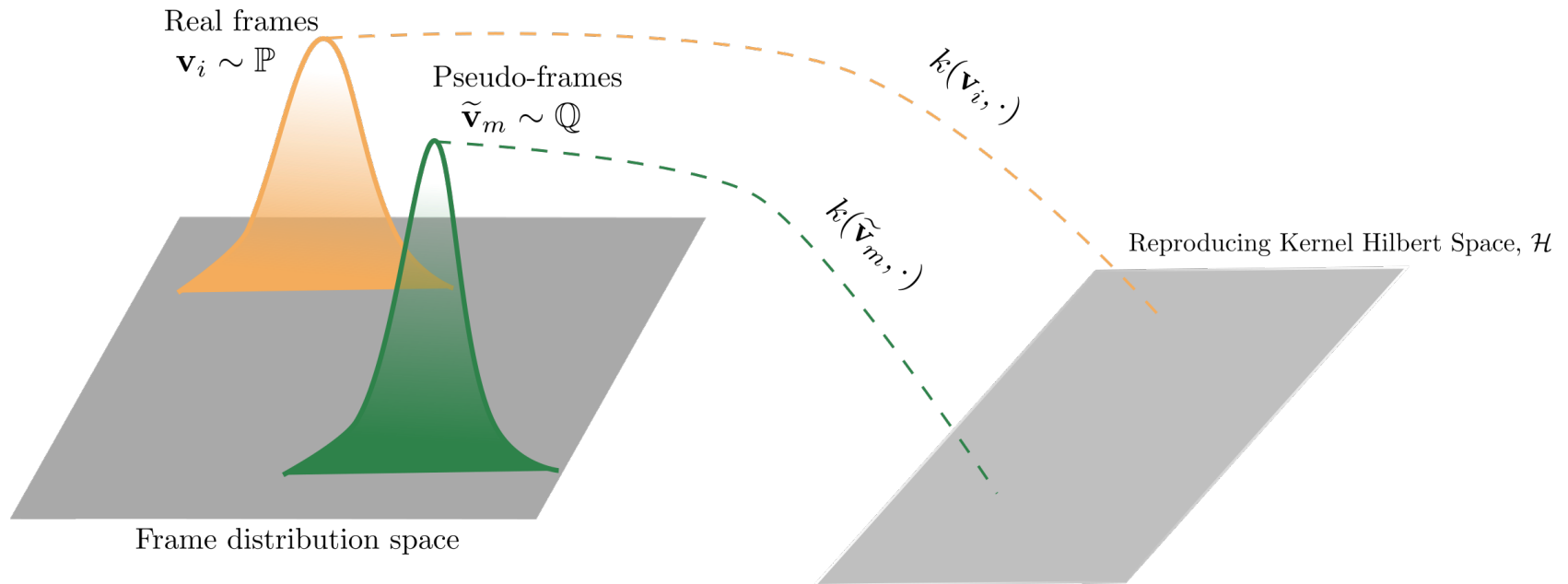
# Metric choice

- "As close as possible"  $\rightarrow$  maximum mean discrepancy (MMD)



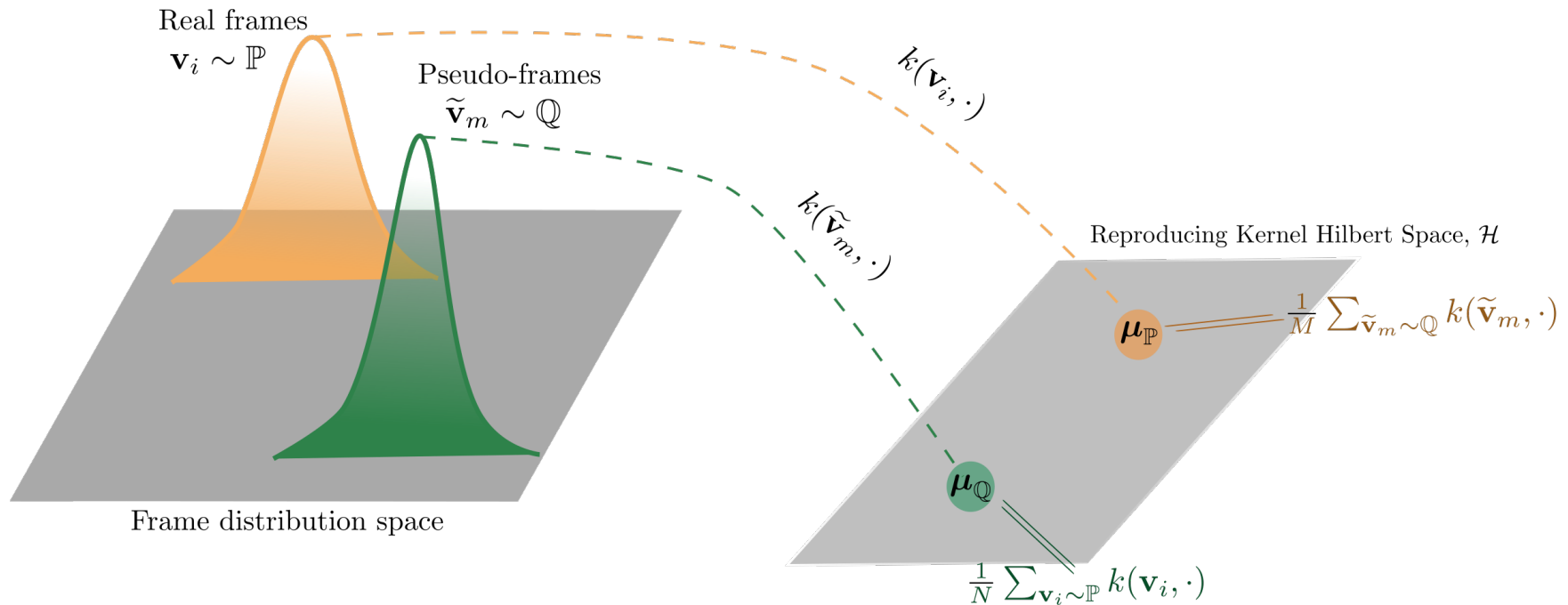
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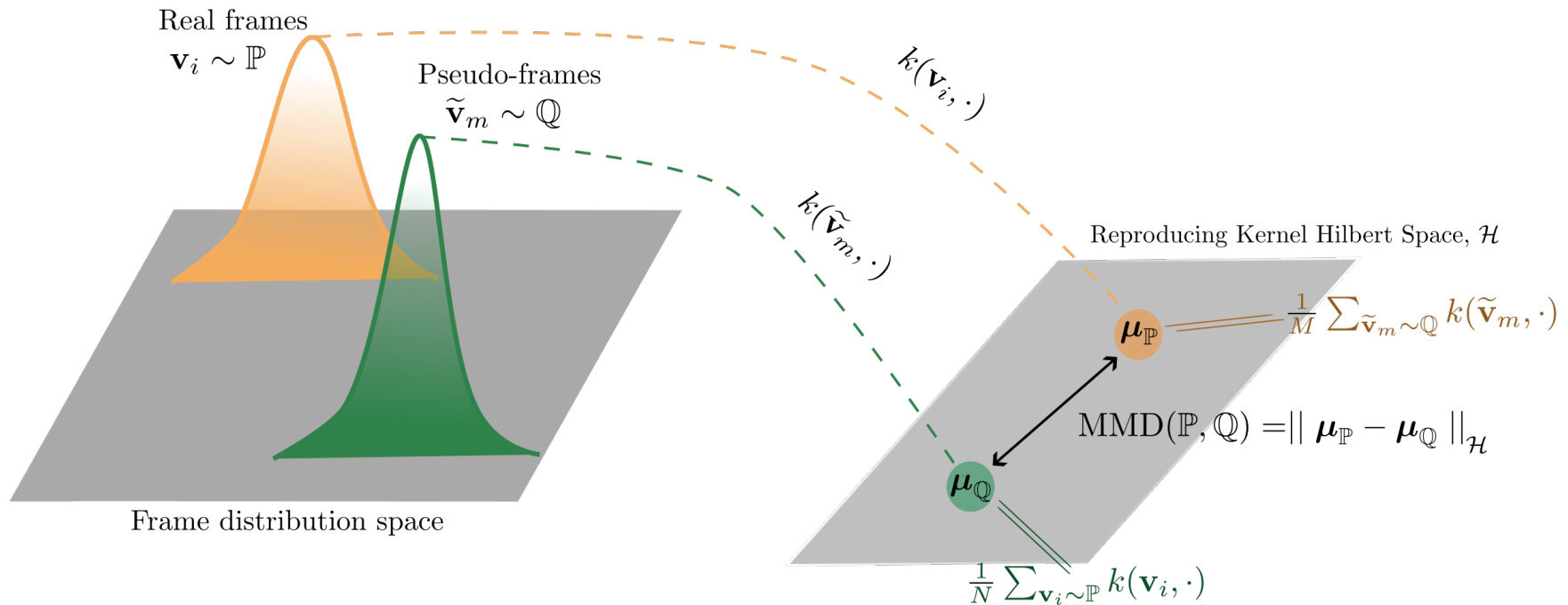
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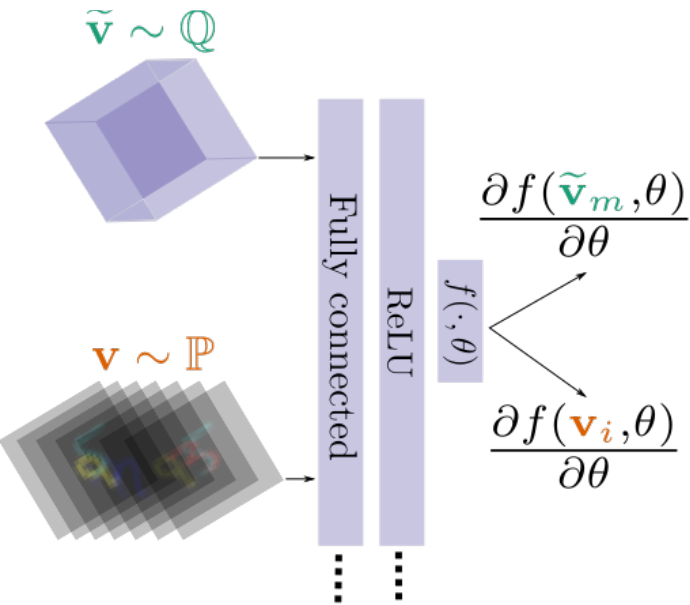


# Kernel choice

- Catch:  $\mu_{\mathbb{P}} = \mu_{\mathbb{Q}} \iff \mathbb{P} = \mathbb{Q}$  only holds for characteristic kernels (s.a. exponential family).
- Infinite NTKs (*S. Arora et. al., NeurIPS, 2019*) are more expressive than fixed exponential kernels (but not characteristic)

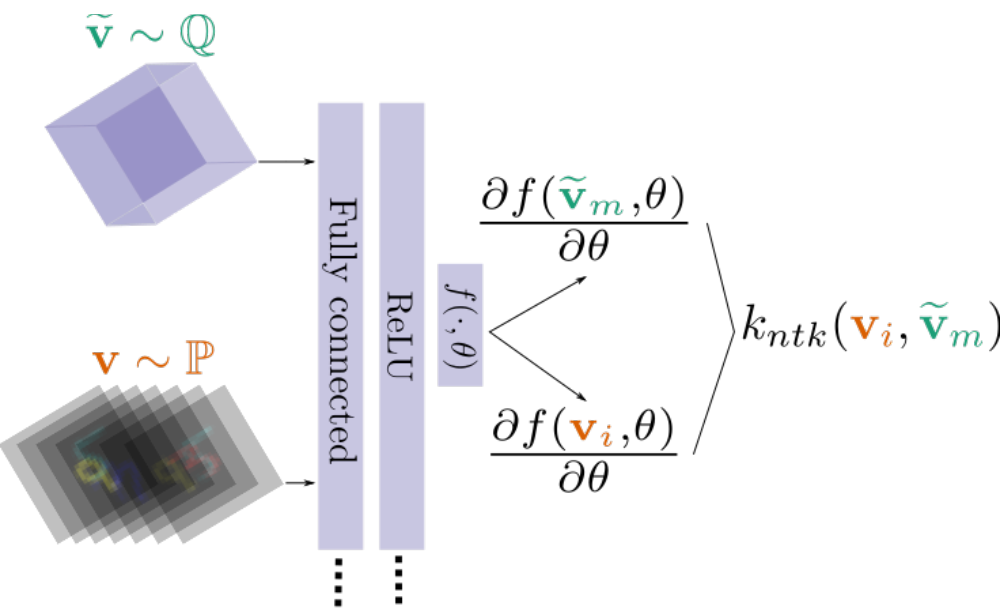
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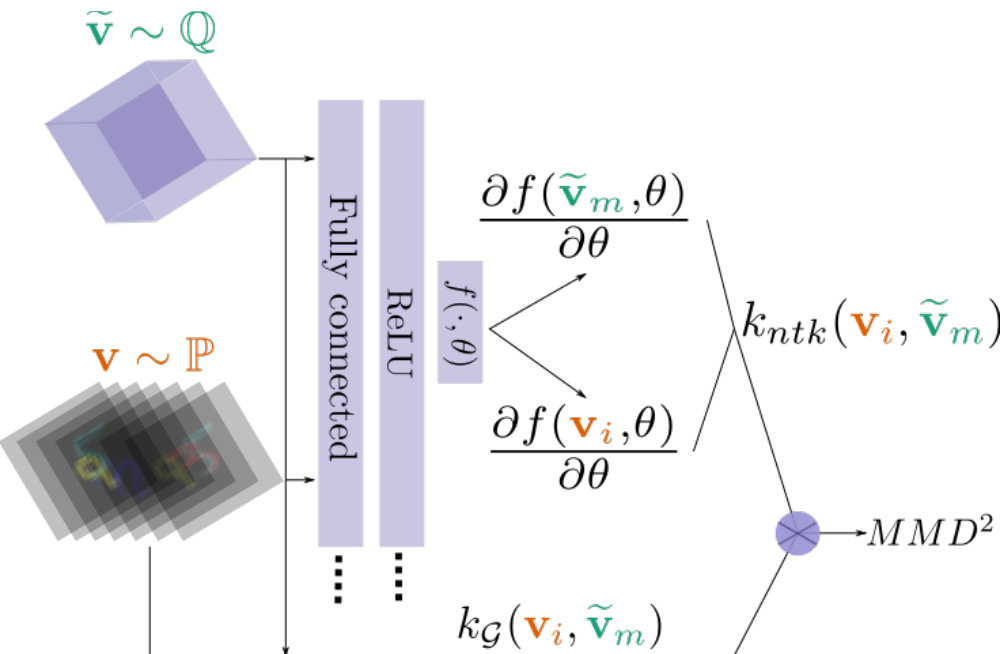
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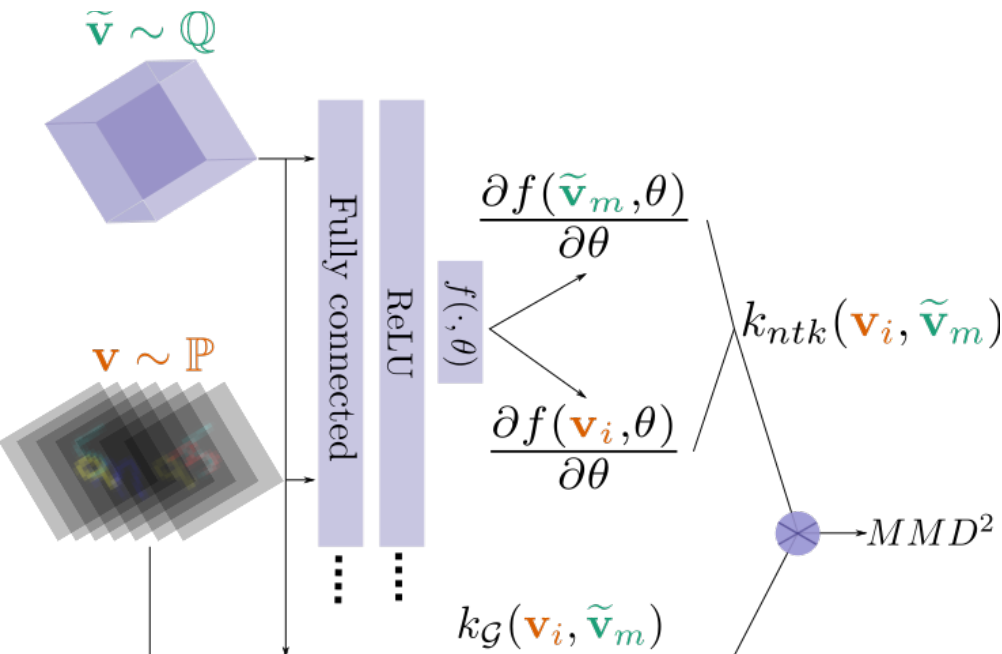
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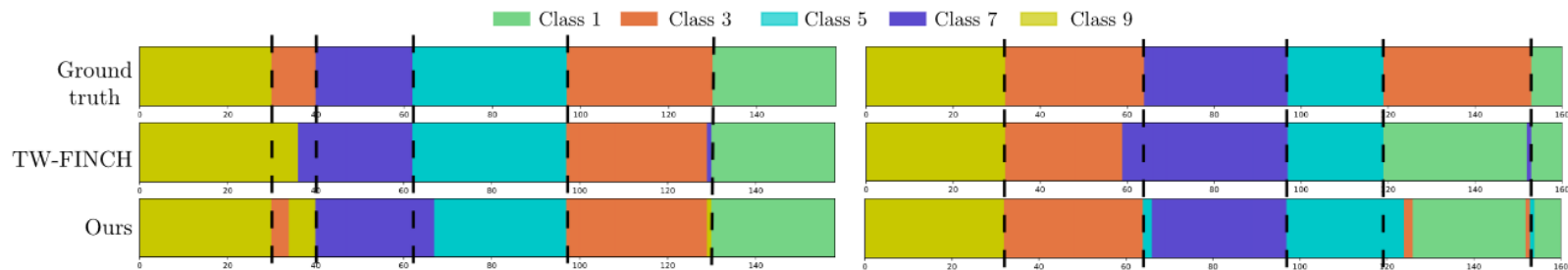


|                           | MoF ( $\uparrow$ ) | IoU ( $\uparrow$ ) | $F_1$ ( $\uparrow$ ) |
|---------------------------|--------------------|--------------------|----------------------|
| Gauss                     | 62.1%              | 46.0%              | 56.7%                |
| NNGP [48]                 | 67.7%              | 46.2%              | 56.6%                |
| NTK [30]                  | 69.1%              | 42.3%              | 52.6%                |
| NTK sphere [33]           | 67.1%              | 46.6%              | 57.3%                |
| SNTK [34] <sup>1</sup>    | 62.7%              | 45.7%              | 56.5%                |
| Gauss $\times$ NTK sphere | 69.8%              | 44.6%              | 55.0%                |
| Gauss $\times$ NTK (Ours) | 70.1%              | 44.9%              | 55.3%                |

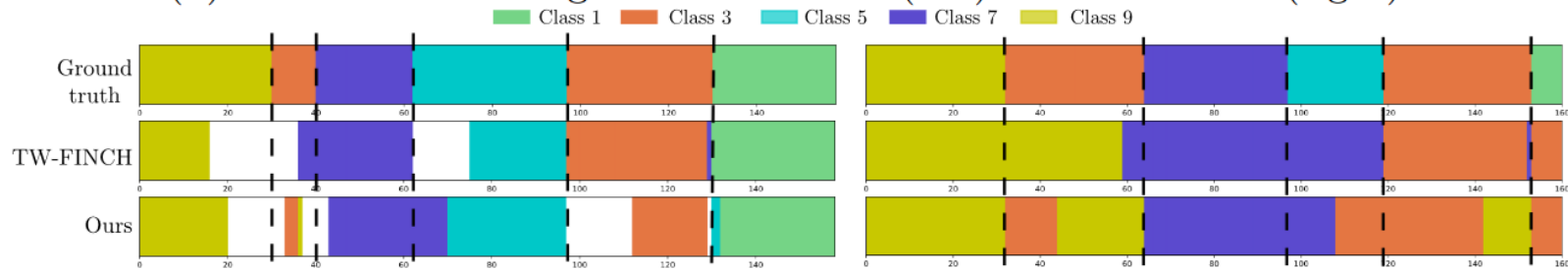
# Does it work?

|              | True # actions     |                              |              | Random # actions   |                              |
|--------------|--------------------|------------------------------|--------------|--------------------|------------------------------|
|              | MoF ( $\uparrow$ ) | Boundary acc. ( $\uparrow$ ) |              | MoF ( $\uparrow$ ) | Boundary acc. ( $\uparrow$ ) |
| TW-FINCH [2] | 72.5%              | 64.4%                        | TW-FINCH [2] | 60.3%              | 58.8%                        |
| Ours         | 73.3%              | 51.2%                        | Ours         | 60.5%              | 62.4%                        |

(a) Segmentation with true classes and random number of classes



(b) True number of segments: 5<sup>th</sup> video (left) and 35<sup>th</sup> video (right).



(c) Random number of segments: more (5<sup>th</sup> video) and less (35<sup>th</sup> video).

# Thank you!

