

XD: eXplainable Drift for LLM's Robustness in Communication Network Protocols Modelling

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Outline

- ▶ Introduction: Context-Problem-Solution
- ▶ Proposed Methods
- ▶ Experiment Results
- ▶ Conclusion and Perspectives

Introduction

Context - Critical Communication Network

► Conventional Network

- Environment → Network Infrastructure / Topology (Data Plane, links, routers)
- Intelligence Layer → Control Plane / Routing Protocols (e.g., OSPF, SDN Controller)
- Algorithms → Optimization Techniques (e.g., Dijkstra's algorithm, Linear Programming)
- Decision Variables → Routing Parameters & Rules (e.g., Link Weights, Next-Hop Tables)

Traditional Network ≠ Critical Network

Critical by strict time constraints & bad decision consequences ...

► For critical application,

- Look for better “Relevant” decision variables ;
- Anticipation is key rather than Reaction in near real-time application.

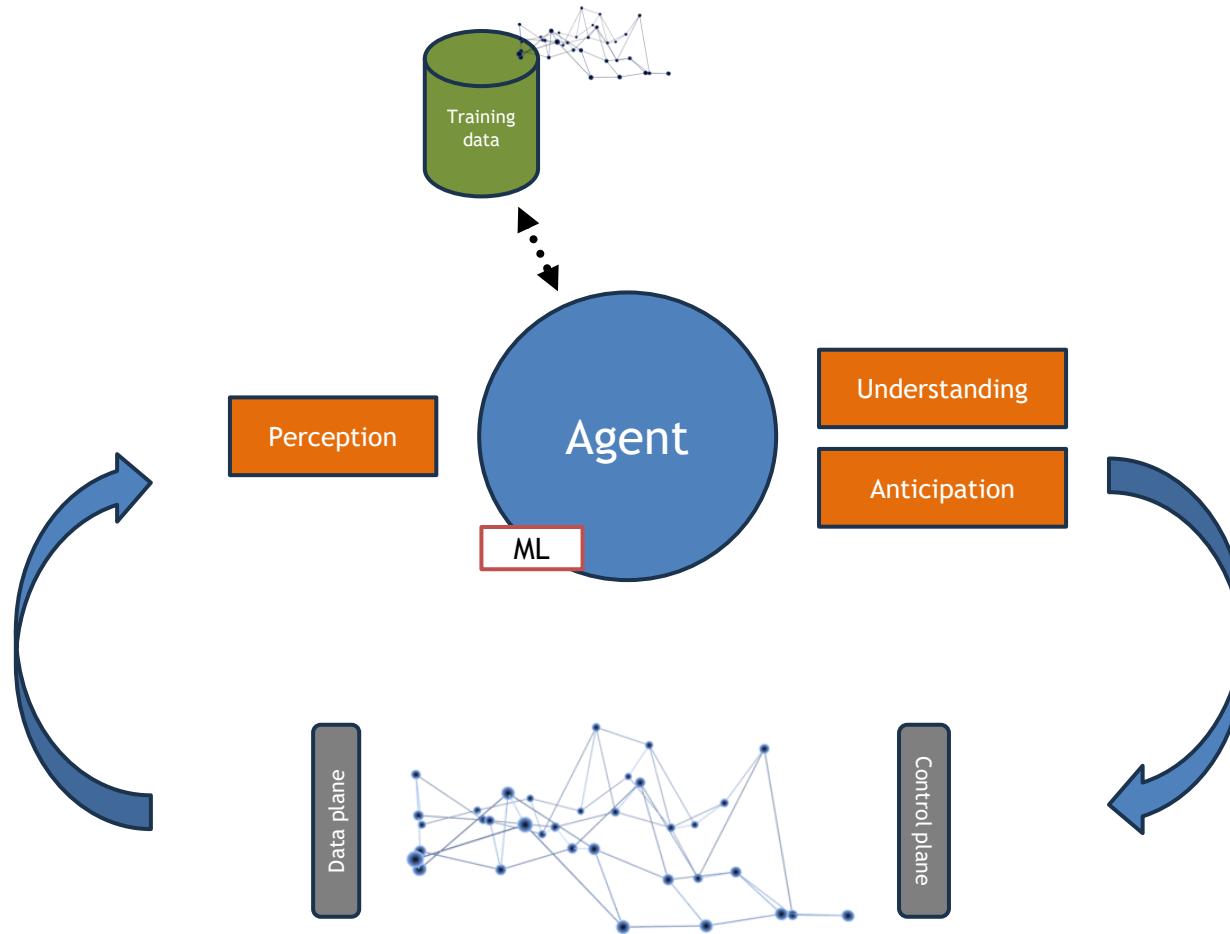
► Technological trends x Operational realities:

- Literature review : LLM is widely used in Telecommunication;
- Operational realities : For network usage monitoring, application protocols are raising greater concerns.



Introduction

High-Level Representation of our System and Task



Task : Predict the network protocols at $t+1$ with reliability and transparency

Introduction

Problem statement

Trustworthy Informed Prediction for Critical Network Control



How does the system operate and be accurate in an uncontrolled critical environment ?

Perception of the
environment;

Understanding of the
environment;

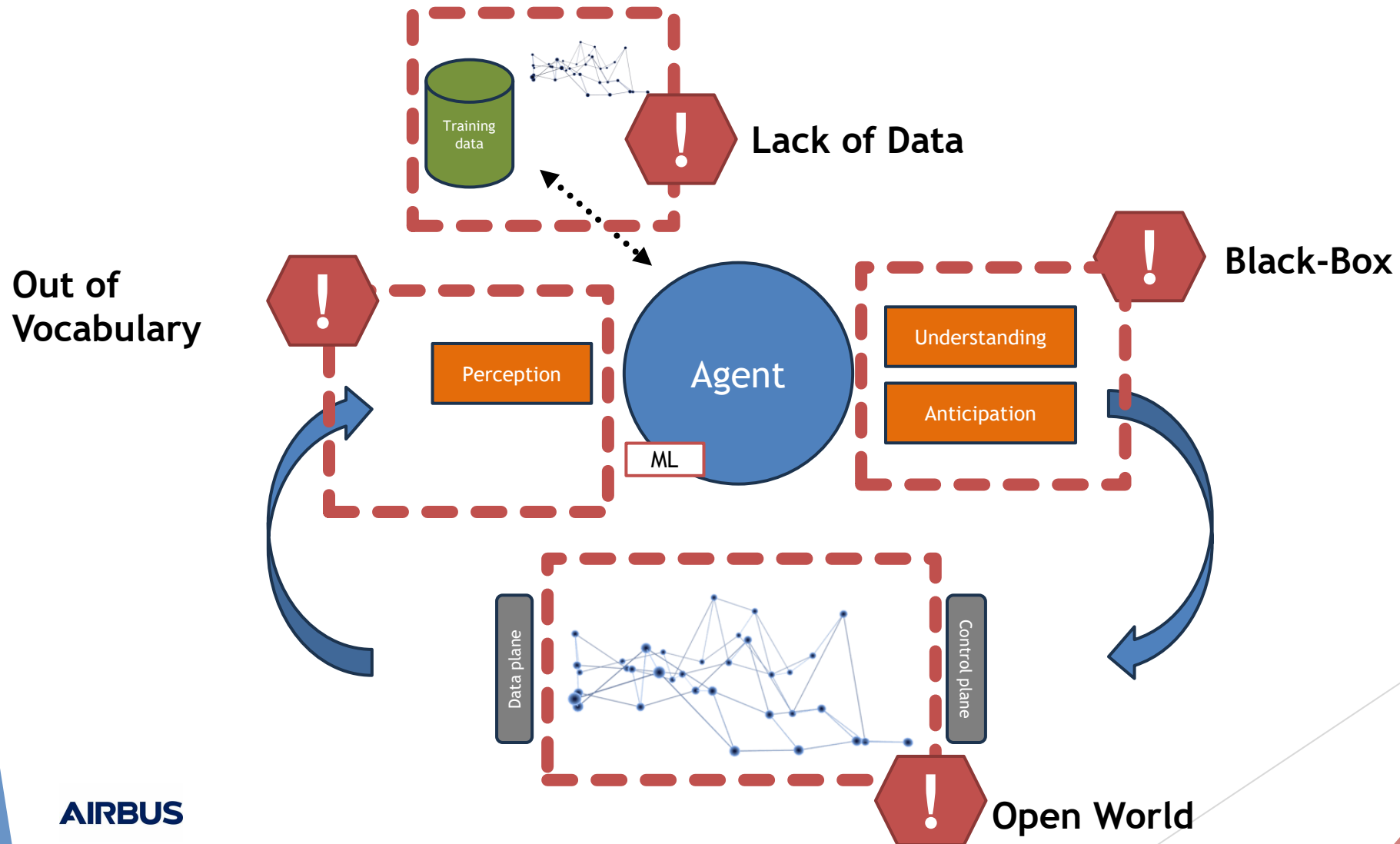
Anticipation of the
environment.



Knowledge Validation

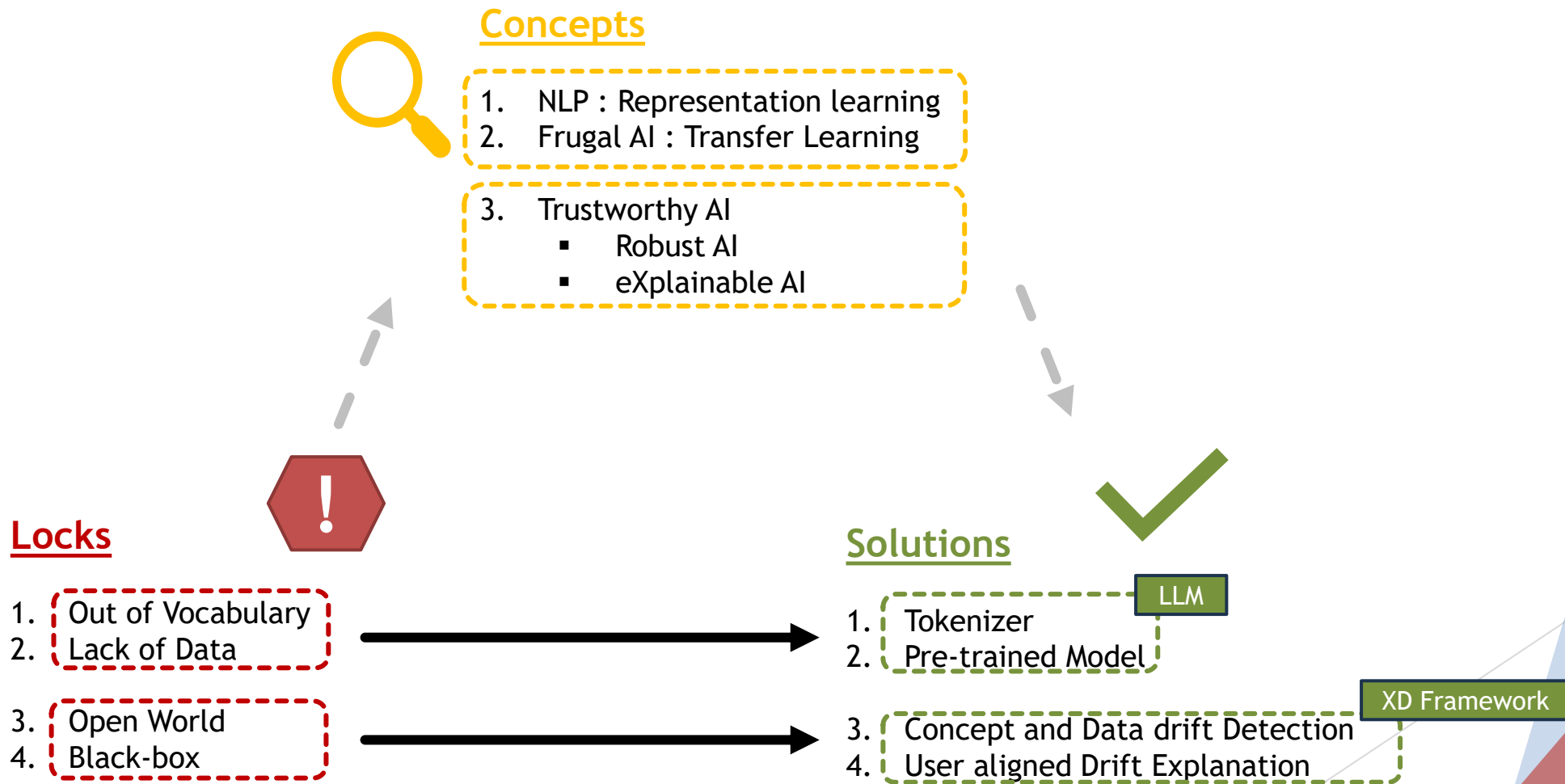
Introduction

High level representation of our System & Locks



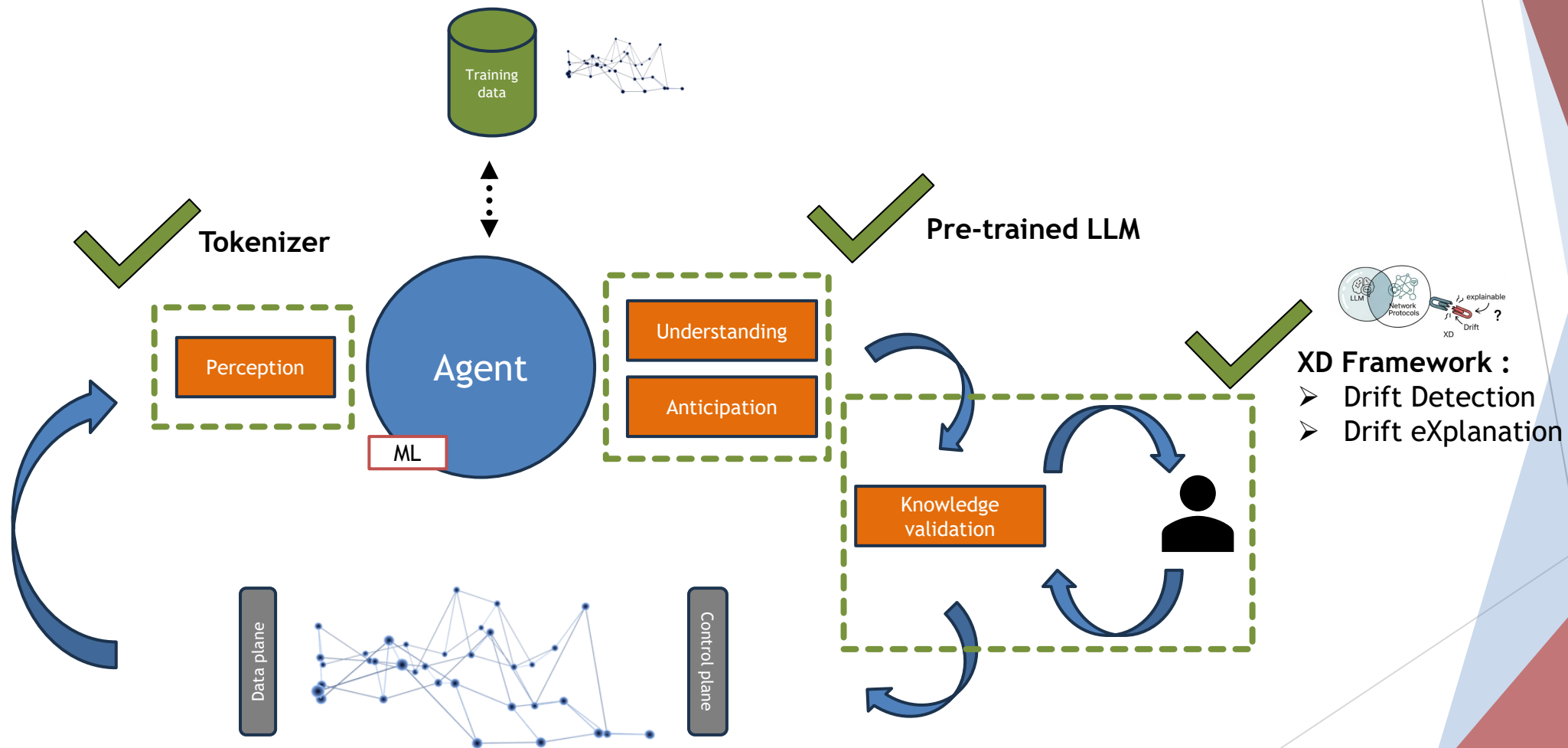
Introduction

From bottlenecks to solutions through established concepts



Introduction

High level representation & solutions



Proposed Methods

The Master overview

Data source and
processing

Generative AI for
Modelling and
Prediction

Multi Level
Behavioral
Monitoring and
Drift Detection

Human
Interpretable
Concept and Data
Drift eXplanation

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Data Source and Processing

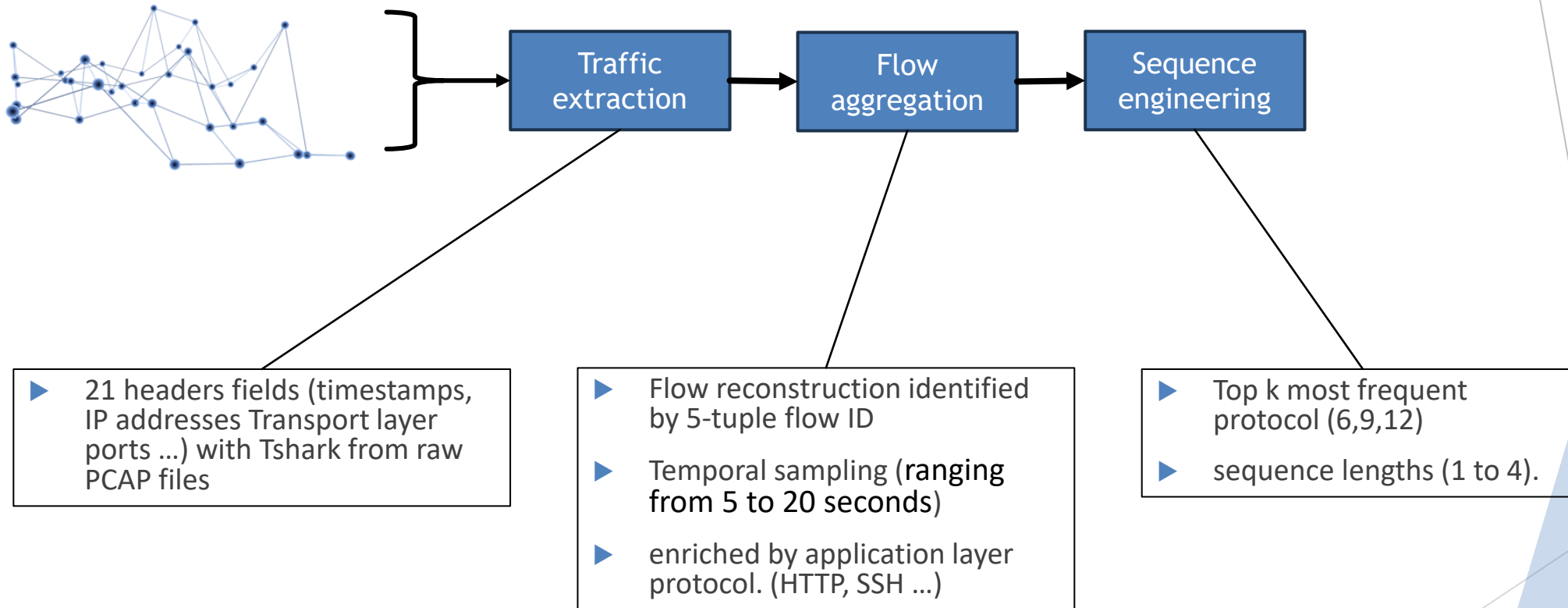
Real World network Traffic Dataset and Simulated Data



- ▶ **MAWI**
 - ▶ This dataset consists of packet traces from a high-speed trans-Pacific backbone link (202304121400 trace daily transit link traffic from WIDE to its upstream ISP)
- ▶ **CAIDA**
 - ▶ This dataset provides large-scale traces from the Equinix-NYC commercial monitor (a 15-minute capture from January 17, 2019 (13:00:00 to 13:15:00 UTC) on high-volume commercial streams.
- ▶ **UNICAUCA**
 - ▶ This dataset (Version 2) focuses on enterprise-level flow-based traffic, offering a distinct protocol distribution to test the model's adaptability across network domains.
- ▶ **Simulated Data**
 - ▶ These sequences are produced via a Markov chain where transitions between protocols (e.g., HTTP, FTP, SSH) are governed by a configurable transition tensor. By modifying the stochastic properties of this tensor, we precisely inject shifts in protocol distribution or transition logic.

Data Source and Processing

Time Series Data Processing for Top-K Protocol Analytics



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Generative AI for Modelling and Prediction

LLM for Protocol Sequence prediction & Evaluation Metrics for Operational reliability

Category	Model	Size
Pioneer Architecture	GPT2	125M
SLM	Phi2	1.2B
	LFM2	2.7B
LLM	Mistral	7B
	Falcon	7B
	Llama-3	8B

- ▶ Protocol Level Performance Metric

$$\text{Prec}_{\text{protocol}} = \frac{1}{N} \sum_{i=1}^N \left(\frac{TP_i}{TP_i + FP_i} \right)$$

- ▶ Sequence-Level Performance Metric

$$\text{Acc}_{\text{sequence}} = \frac{TP_{\text{total}}}{TP_{\text{total}} + FP_{\text{total}}}$$

- ▶ Relative Performance Metrics

$$\Delta_{\text{metric}} = \frac{\text{Metric}_{\text{model}} - \text{Metric}_{\text{base}}}{\text{Metric}_{\text{base}}} = \frac{\text{Metric}_{\text{model}}}{\text{Metric}_{\text{base}}} - 1$$

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Multi Level Behavioral Monitoring and Drift Detection

Model Pattern Representation, Bias and Discrepancy Metrics, and Drift Detection

► Model Pattern Representation : $T_{uv} = \mathbb{P}(p_{t+1} = v \mid p_t = u) = \frac{\text{count}(u \rightarrow v)}{\sum_{w \in \mathcal{S}} \text{count}(u \rightarrow w)}$

► Model Bias and Discrepancy Metrics

► E-wise Cross Entropy : $CE(Q, P)_{ij} = -Q_{ij} \ln(P_{ij} + \epsilon)$

► E-wise Symmetric KL Divergence : $D_{SKL}(P, Q)_{ij} = \frac{1}{2} \left(P_{ij} \ln \frac{P_{ij}}{Q_{ij}} + Q_{ij} \ln \frac{Q_{ij}}{P_{ij}} \right)$

► E-wise Hellinger Distance : $H(P, Q)_{ij} = \frac{1}{\sqrt{2}} \sqrt{(\sqrt{P_{ij}} - \sqrt{Q_{ij}})^2}$

► Model Drift Detection : $D_t = \text{stat}(d(B_{gold}, B_t)) \quad \& \quad \bar{D}_t = \frac{1}{k} \sum_{i=0}^{k-1} D_{t-i}$

Multi Level Behavioral Monitoring and Drift Detection

Threshold Calibration Modes and Anomaly Detection Evaluation Metrics

► Threshold Calibration Modes

- **Manual (man):** $\tau = \lambda$, where λ is a user-defined constant.
- **Semi-Supervised (semi):** $\tau = \mu_D + (\alpha \cdot \sigma_D)$, where α is a sensitivity coefficient.
- **Unsupervised (full):** $\tau = \mu_D + (\kappa \cdot \sigma_D)$, where κ is automatically adjusted using a buffer β :

$$\kappa = \frac{\max(D_{internal}) - \mu_D}{\sigma_D} + \beta \quad (12)$$

A drift event is signaled at time t if the smoothed drift score exceeds the calibration threshold τ : $\bar{D}_t > \tau$.

► Anomaly Detection Evaluation Metrics

- Accuracy & Threshold-independent Area under the Curve

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Human Interpretable Concept and Data Drift eXplanation

Concept Drift Analysis, Data Drift Analysis ,and Filtering and Complexity Management

► Concept Drift Analysis (Nodes)

- **Appearing Concepts ($\mathcal{C}_{appear}$):** Protocols that are newly observed in the current window.

$$\mathcal{C}_{appear} = \{s \mid s \in \mathcal{S}_{curr} \wedge s \notin \mathcal{S}_{prev}\} \quad (13)$$

- **Disappearing Concepts ($\mathcal{C}_{disappear}$):** Protocols that were present in the previous state but are no longer active.

$$\mathcal{C}_{disappear} = \{s \mid s \in \mathcal{S}_{prev} \wedge s \notin \mathcal{S}_{curr}\} \quad (14)$$

- **Stable Concepts ($\mathcal{C}_{stable}$):** Protocols that persist across both windows.

$$\mathcal{C}_{stable} = \mathcal{S}_{curr} \cap \mathcal{S}_{prev} \quad (15)$$

► Data Drift Analysis (Edge)

$$\text{Edge_Status}(u, v) = \begin{cases} \text{Data Drift (Red)} & \text{if } B_{t,uv} > \tau_{ref} \\ \text{Stable (Gray)} & \text{otherwise} \end{cases} \quad (16)$$

► Filtering and Complexity Management

► Node Based Filtering

$$\Psi_{node}(u) = \sum_{v \in \mathcal{S}} |T_{uv}| + \sum_{v \in \mathcal{S}} |T_{vu}|$$

► Link based Filtering

$$\Psi_{link}(u, v) = |T_{uv}|$$

Experiment Results

Experimental methodology step-by-step

01

Comparison
Study of LLMs
for Protocol
Sequence
Prediction

02

Offline
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Retrospective
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Comparison Study of LLMs for Protocol Sequence Prediction

Table 1. Comprehensive Experimental Results across MAWI, CAIDA, and Unicauca Datasets

Dataset	Category	Model	Task-specific (Raw)		Real-World (Relative Δ)	
			Prot-lev	Seq-lev	Prot RP (Δ)	Seq RP (Δ)
MAWI	Pioneer LM	GPT2	0.8488	0.3704	8.70%	25.00%
	SLM	Phi2	0.8272	0.4074	5.93%	37.50%
		LFM2-1.2b	0.8364	0.3704	7.11%	25.00%
	LLM	Mistral-7B	0.8272	0.3333	5.93%	12.50%
		Falcon-7b	0.8117	0.1852	3.95%	−37.50%
		Llama3-8b	0.8241	0.2963	5.53%	0.00%
CAIDA	Pioneer LM	GPT2	0.9080	0.4828	3.61%	16.67%
	SLM	Phi2	0.9167	0.5172	4.59%	25.00%
		LFM2-1.2b	0.9167	0.5172	4.59%	25.00%
	LLM	Mistral-7B	0.9023	0.4483	2.95%	8.33%
		Falcon-7b	0.9167	0.5172	4.59%	25.00%
		Llama3-8b	0.9023	0.4828	2.95%	16.67%
Unicauca	Pioneer LM	GPT2	0.4223	0.0000	11.68%	Nan
	SLM	Phi2	0.4211	0.0000	11.36%	Nan
		LFM2-1.2b	0.4186	0.0001	10.72%	Nan
	LLM	Mistral-7B	0.4178	0.0053	10.51%	Nan
		Falcon-7b	0.4113	0.0000	8.79%	Nan
		Llama3-8b	0.4101	0.0053	8.47%	Nan

Table 2. Summary of Average Real-World Performance Across Datasets

Category	Models	Av prot RP	Av seq RP w/o Unicauca
Pioneer LM	GPT2	8.00%	20.84%
SLM	Phi2	7.29%	31.25%
	LFM2-1.2b	7.47%	25.00%
LLM	Mistral-7B	6.46%	10.42%
	Falcon-7b	5.78%	−6.25%
	Llama3-8b	5.65%	8.34%

$$\Delta_{\text{metric}} = \frac{\text{Metric}_{\text{model}}}{\text{Metric}_{\text{base}}} - 1 \approx 0$$

Experiment Results

Comparison Study of LLMs for Protocol Sequence Prediction

Table 4. Summary of Real-World Performance by Sequence Length (Seq)

Seq	MAWI		CAIDA		Unicauca		Averages	
	Prot RP	Seq RP	Prot RP	Seq RP	Prot RP	Seq RP	Av Prot	No Uni
1	5.14%	25.00%	-1.31%	-25.00%	8.72%	Nan	4.18%	0.00%
2	5.93%	37.50%	4.59%	25.00%	11.36%	Nan	7.29%	31.25%
3	2.77%	25.00%	-2.62%	-25.00%	17.41%	Nan	5.85%	0.00%
4	1.58%	-25.00%	2.62%	25.00%	23.60%	Nan	9.27%	0.00%

Table 3. Summary of Real-World Performance by Interval (i)

Interval	MAWI		CAIDA		Unicauca		Averages	
	Prot RP	Seq RP	Prot RP	Seq RP	Prot RP	Seq RP	Av Prot	Av Seq
i5	5.93%	37.50%	4.59%	25.00%	11.36%	Nan	7.29%	20.83%
i10	13.89%	0.00%	1.90%	60.00%	6.31%	0.00%	7.37%	20.00%
i15	-10.42%	25.00%	9.62%	28.57%	9.33%	0.00%	2.84%	17.86%
i20	-1.61%	Nan	4.65%	-25.00%	0.28%	Nan	1.11%	-8.33%

Table 5. Summary of Performance by Number of Protocols (n_prot)

n_prot	MAWI		CAIDA		Unicauca		Averages	
	Prot RP	Seq RP	Prot RP	Seq RP	Prot RP	Seq RP	Av Prot	No Uni
6	0.8553	-0.6458	-0.1235	-0.4138	1.10%	-100%	24.76%	-52.98%
9	0.803	-0.7083	-0.0458	-0.125	9.12%	600%	28.28%	-41.67%
12	5.93%	37.50%	4.59%	25.00%	11.36%	Nan	7.29%	31.25%

Phi-2 with an interval of $i= 5$, $Seq= 2$, and $n_prot= 12$

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Offline Evaluation for Retrospective Drift Analysis

Data drift between two well known concepts

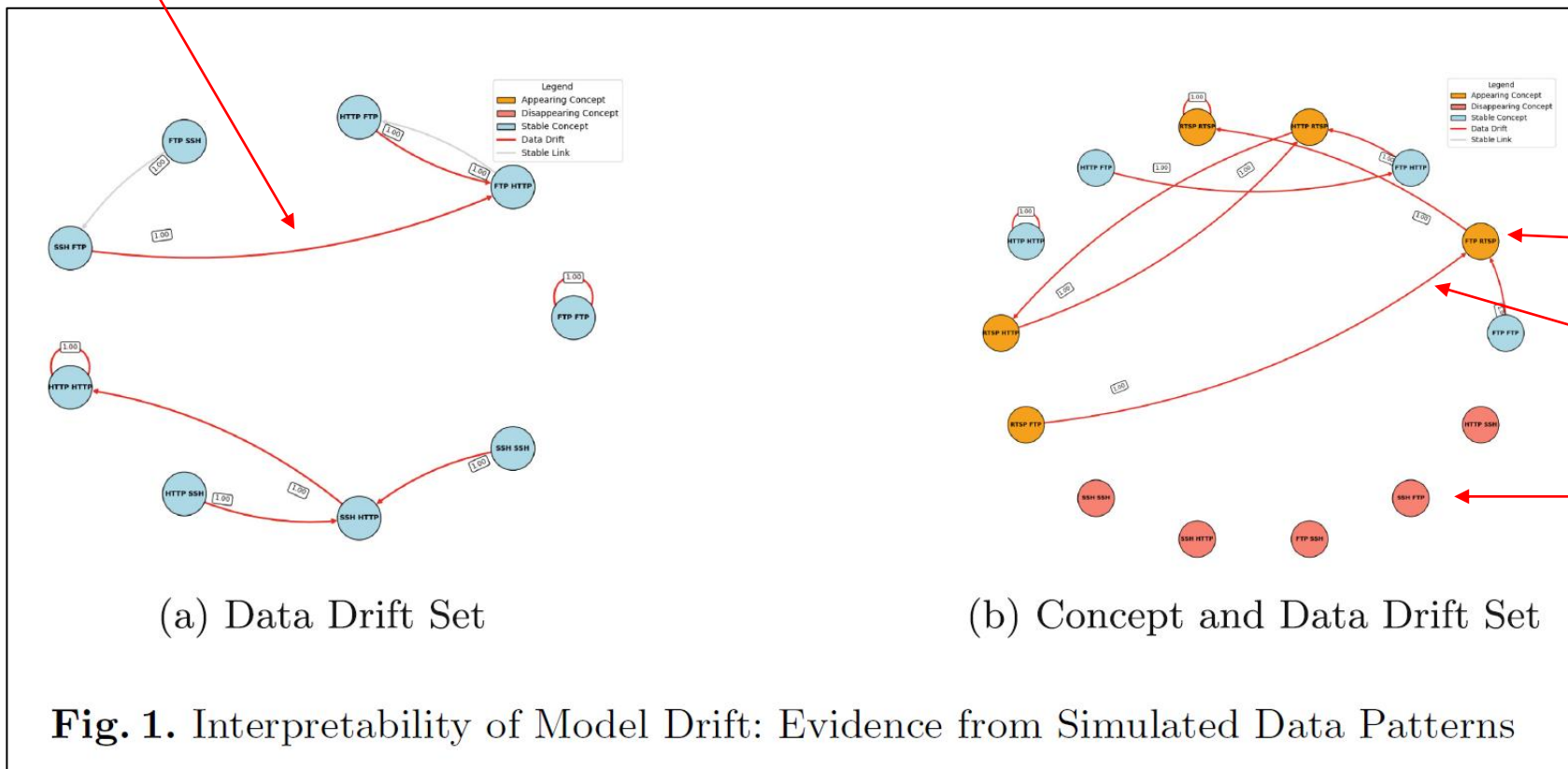
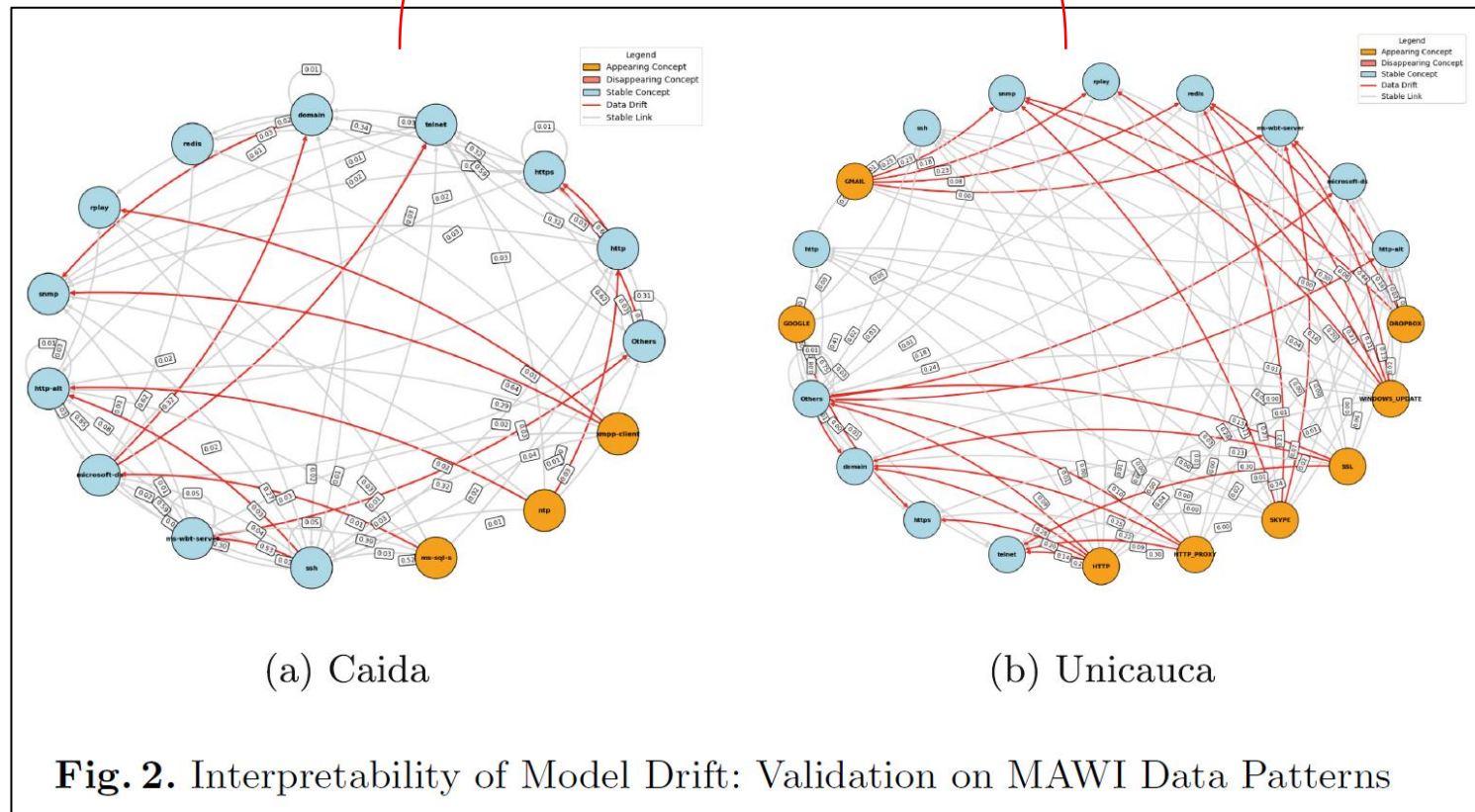


Fig. 1. Interpretability of Model Drift: Evidence from Simulated Data Patterns

Experiment Results

Offline Evaluation for Retrospective Drift Analysis

Visualization complexity management → Top k Node



Experiment Results

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Online Evaluation for Real-time Drift Analysis

Table 6. Top 15 Results of Grid Search for Drift Detection Configurations

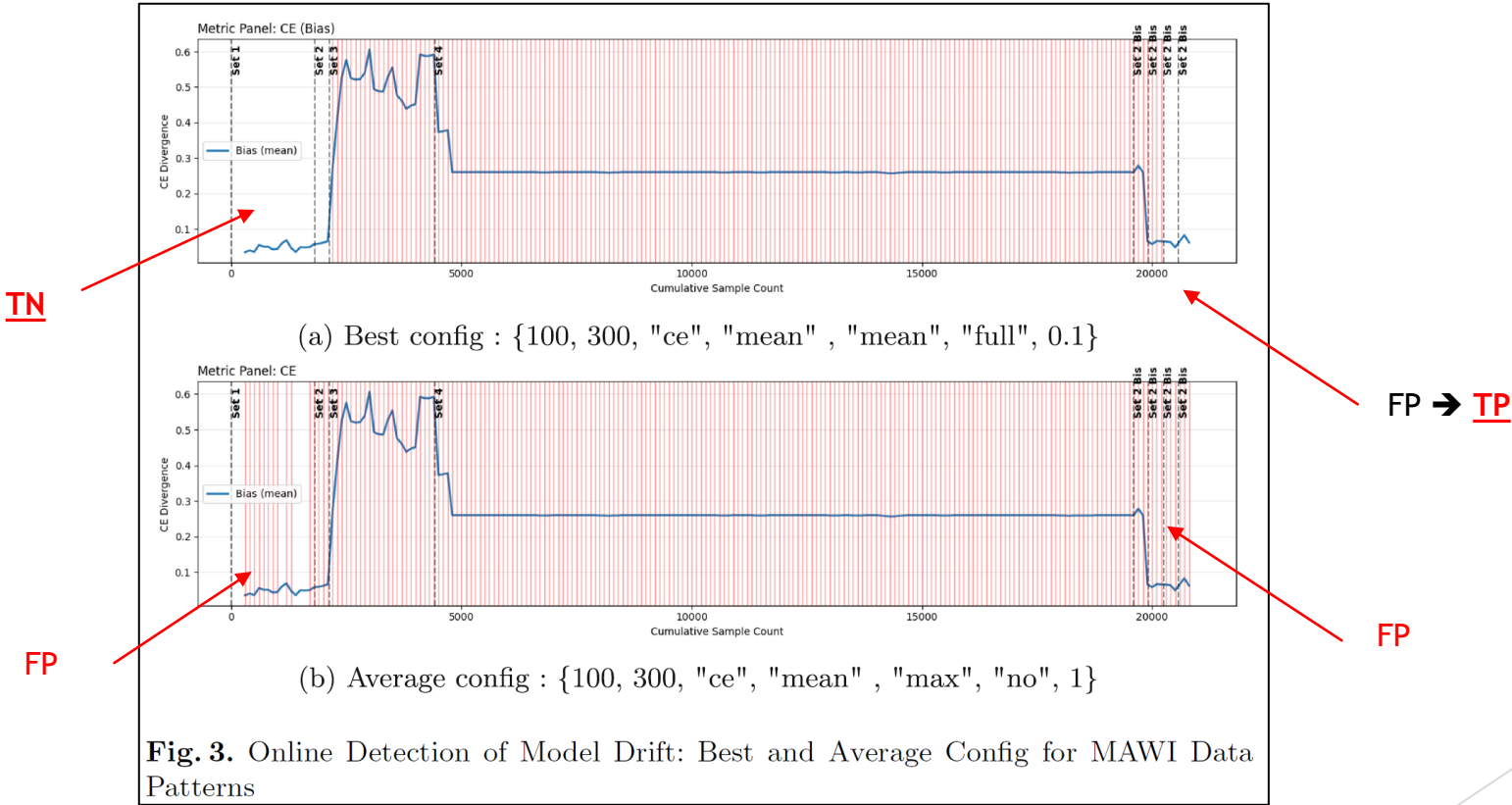
Step	Win.	Metric	Bias	Drift	Mode	Sens.	Buf.	Thresh.	Accuracy	AUC
100	300	CE	Mean	Mean	Semi	3.0	—	—	0.985	1.000
100	300	CE	Mean	Mean	Semi	4.0	—	—	0.985	1.000
100	300	CE	Mean	Mean	Full	—	0.1	—	0.985	1.000
100	300	CE	Max	Mean	Semi	3.0	—	—	0.985	1.000
100	300	CE	Max	Mean	Semi	4.0	—	—	0.985	1.000
100	300	CE	Max	Mean	Full	—	0.1	—	0.985	1.000
100	300	CE	Mean	Max	No	—	—	3	0.985	0.933
100	300	CE	Max	Max	No	—	—	3	0.985	0.933
50	300	CE	Mean	Mean	Semi	3.0	—	—	0.982	0.999
50	300	CE	Mean	Mean	Semi	4.0	—	—	0.982	0.999
50	300	CE	Mean	Mean	Full	—	0.1	—	0.982	0.999
50	300	CE	Max	Mean	Semi	3.0	—	—	0.982	0.999
50	300	CE	Max	Mean	Semi	4.0	—	—	0.982	0.999
50	300	CE	Max	Mean	Full	—	0.1	—	0.982	0.999
50	300	CE	Mean	Max	No	—	—	3	0.982	0.895

Best

Average

Experiment Results

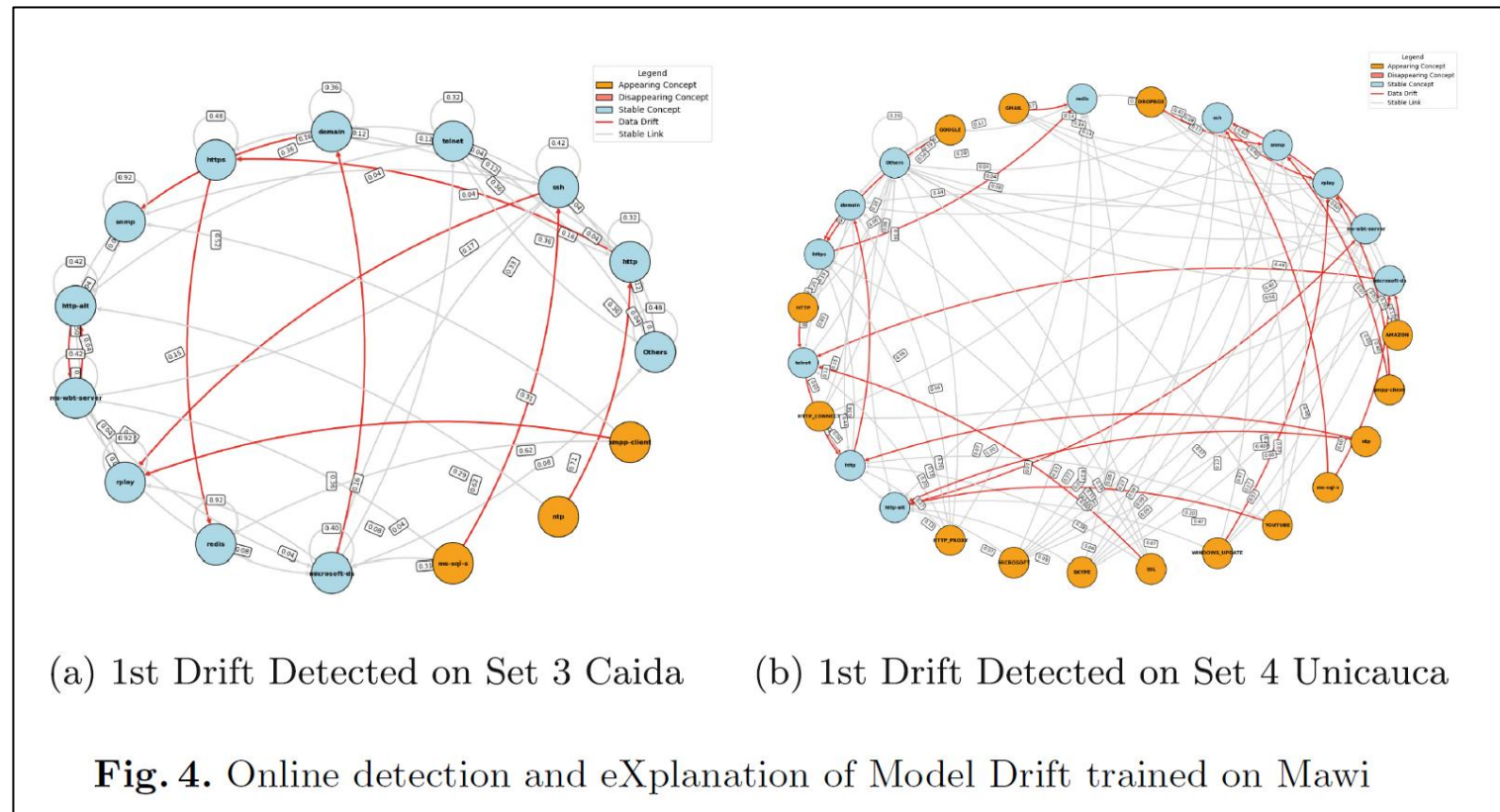
Online Evaluation for Real-time Drift Analysis



Experiment Results

Online Evaluation for Real-time Drift Analysis

Still accurate in online detection and eXplanation (≈ 300 online observations)
even if not the full dataset



Conclusion

► Feasibility Study → Tokenizer and LLM for Network Protocols Prediction

- Universal Representation
- Transfer Learning

} Relative performance shows the added value in real world scenarios of network protocol prediction.

► Proof of Concept → XD model-agnostic framework

- Pattern Modeling for Autoregressive Models;
- Unsupervised thresholding mechanism for Drift Detection;
- Concept and Data Drift Visual eXplanation.

Results show that **XD** successfully bridges the gap between high-dimensional statistical shifts and user-centric topological explanations.

► On-going works

- Extend framework for continues-value time series, and extend to broader NLP tasks.

Thank You !

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<https://gitlab.ailab.airbus.com/abhishek/xd4llm>